

SESSION 1 REVIEW OF PROBABILITY

Define $S \equiv$ the sample space, the set of all possible outcomes of an experiment

"experiment" should be thought of broadly ~~as~~
of data-generating process (DGP)
could be discrete, could be ctr.

let \mathcal{A} be a family of sets, each a subset of S .

\mathcal{A} is a σ -field iff:

- ① $S \in \mathcal{A}$
- ② if $A \in \mathcal{A}$, then $A^c \in \mathcal{A}$
- ③ if A_1, A_2, \dots is an infinite sequence $\in \mathcal{A}$, then

$$\bigcup_{i=1}^{\infty} A_i \in \mathcal{A}$$

Sets in \mathcal{A} are called events.

IF S is ~~finite~~ finite or countable, then \mathcal{A} includes all subsets of

IF S is \mathbb{R}^n , \mathcal{A} is the σ -field of Borel sets, which is just the smallest σ -field containing all n -dim intervals

2 count
ex.

Def. a probability distribution P on (S, \mathcal{A}) is a non-negative fn. defined for each ~~event~~ event in \mathcal{A} w/ the following:

- ① $P(S) = 1$
- ② IF A_1, A_2, \dots is a sequence of disjoint events

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$$

(S, \mathcal{A}, P) is called a probability space.

Continue
ex.
.7 .05
.05 .2

st
1/4
1/4

Some things to prove about properties of P:

- (a) If A_1, \dots, A_n are disjoint events, then $P(\bigcup_{i=1}^n A_i) = \sum_{i=1}^n P(A_i)$
- (b) $P(\phi) = 0$
- (c) $P(A^c) = 1 - P(A)$
- (d) If $A \subset B$ are two events, then $P(A) \leq P(B)$
- (e) If A_1, A_2 are events, then $P(A_1 \cup A_2) = P(A_1) + P(A_2) - P(A_1 A_2)$
- (f) If $A_1 \subset A_2 \subset \dots$ is a sequence of events, then $P(\bigcup_{i=1}^{\infty} A_i) = \lim_{n \rightarrow \infty} P(A_n)$

Linda is 31, single, outspoken, and very bright. She majored in philosophy in college. As a student, she was deeply concerned with racial discrimination and other social issues, and participated in anti-nuclear demonstrations.

Rank the likelihood of various alternatives

- ① Linda is active in the feminist movement.
- ② Linda is a bank teller.
- ③ Linda is a bank teller and active in the feminist movement.

Conditional Probability (discrete)

Conditional probability of $A|B = P(A|B) = \frac{P(A \cap B)}{P(B)}$ if $P(B) > 0$

Ex. 2 coins in my pocket, one fair, one 2-headed
choose 1 at random and flip, it's heads
what is the probability it was the fair coin?

On your own: same question, but

(b) second flip also heads

(c) 3rd flip is tails

Bayes' theorem

perhaps the most important one ~~of all~~ of all

Let A_1, A_2, \dots be an infinite sequence of disjoint events s.t.

$\bigcup_{i=1}^{\infty} A_i = S$ and $\Pr(A_i) > 0 \forall i$, and let B be an event w/ $\Pr(B) > 0$:

Then $\Pr(A_i | B) = \frac{\Pr(B | A_i) \Pr(A_i)}{\sum_{j=1}^{\infty} \Pr(B | A_j) \Pr(A_j)}$

posterior probabilities

$\sum_{j=1}^{\infty} \Pr(B | A_j) \Pr(A_j)$

Sometimes called prior probabilities

Pf. Fix i .

By def of conditional prob, $\Pr(A_i | B) = \frac{\Pr(A_i \cap B)}{\Pr(B)} = \frac{\Pr(BA_i)}{\Pr(B)}$

and also $\Pr(BA_i) = \Pr(B | A_i) \Pr(A_i)$

By ~~def~~ the properties of the sequence, $B = \bigcup_{j=1}^{\infty} BA_j$

Since these events are disjoint, $\Pr(B) = \sum_{j=1}^{\infty} \Pr(BA_j) = \sum_{j=1}^{\infty} \Pr(B | A_j) \Pr(A_j)$ QED

Bayes thm example

- ① revisit the fair vs. 2-headed coin example
- ② A disease hits 1 in 10,000 people.
There's a test that's 90% accurate.
You take the test and it comes back positive.
What's the cond'l prob you have the disease?

independence

Def A and B are indep. if $Pr(AB) = Pr(A)Pr(B)$

ex. (easy) 2-coin flip

ex. (harder) ~~roll~~ throw a fair 6-sided die
 event A: even number
 event B: 1, 2, 3, or 4
 Are A & B indep?

intuition: if info on B is of no help in predicting A, indep!
 ← anything about it

Measurable Functions

Given S and \mathcal{A} , let g be a fn. defined at all points of $S \rightarrow \mathbb{R}$.
 $\forall x \in \mathbb{R}$, let A_x be the subset of S defined by

$$A_x = \{s : g(s) \leq x\}$$

Then g is measurable w.r.t. \mathcal{A} , or \mathcal{A} -measurable, if $A_x \in \mathcal{A}$
 $\forall x \in \mathbb{R}$.

Intuition: think of measurability w.r/t an information set.
 It's measurable if it's well defined based on the current
 granularity of \mathcal{A}

Ex. 2-coin sequential flip; after 1 flip, fn of second flip

Random Variables

Given a prob. space (S, \mathcal{A}, P) , a random variable is
 an \mathcal{A} -measurable fn w/value $X(s) \forall s \in S$

Since X is a $f: S \rightarrow \mathbb{R}$, it induces a probability dist'n on \mathbb{R}

That is, for any Borel set $B \subset \mathbb{R}$

$$P_x(B) = Pr(X \in B) = Pr\{s : X(s) \in B\}$$

Distribution function (or cumulative d.f. "CDF"): a fn. F
 s.t. $F(t) = Pr(X \leq t)$

Properties of F :

- non decreasing
- rt. continuous

$$\lim_{t \rightarrow -\infty} F(t) = 0$$

$$\lim_{t \rightarrow \infty} F(t) = 1$$

Discrete distns

have a probability mass fn (PMF) $f(x) = \Pr(X=x)$

and so $P_x(B) = \sum_{i: x_i \in B} f(x_i)$

Abs. cts. distns

r.v. X has an abs. cts. distn if \exists non-neg. prob. density fn (PDF) f s.t. \forall Borel sets $B \subset \mathbb{R}$,

$$P_x(B) = \int_B f(x) dx$$

Properties: CDF can be differentiated almost everywhere $F'(x) = f(x)$

m -variate distns are just the prob. distn of (2 or more) r.v.'s. joint distn fn or joint CDF defined as

$$F(x_1, \dots, x_m) = \Pr(X_1 \leq x_1, \dots, X_m \leq x_m)$$

For abs cts distns, the pdf is $f(x_1, \dots, x_m)$ s.t. \forall Borel $B \subset \mathbb{R}^m$
 $\Pr[(X_1, \dots, X_m) \in B] = \int_B \dots \int f(x_1, \dots, x_m) dx_1 \dots dx_m$

Measure theory unites ~~the~~ discrete & abs. cts. distns w/ notation

$$\int_B g(x) f(x) d\mu(x) \quad \text{For Borel } B \text{ (in } \mathbb{R} \text{ or sometimes } \int_B g(x) dF(x)$$

For discrete distns, this ~~is~~ means

$$\sum_{x \in B} g(x) f(x) \quad \leftarrow \text{PMF}$$

For abs cts distns

$$\int_B g(x) f(x) dx \quad \leftarrow \text{pdf}$$

Quantile functions Let F be a CDF

Def. p quantile is $\min x : F(x) \geq p$.
often written as $x = F^{-1}(p)$

$p = \frac{1}{2}$ median

$p = \frac{1}{4}$ lower quartile

$p = \frac{3}{4}$ upper quartile

ex.

Val

marginal dist'n - joint dist'n of a subset of the m -tuple X_1, \dots, X_m
 let $1 \leq k < m$. Then

CDF

$$F_k(x_1, \dots, x_k) = \Pr(X_1 \leq x_1, \dots, X_k \leq x_k) \\ = \lim_{x_{k+1}, \dots, x_m \rightarrow \infty} F_m(x_1, \dots, x_m)$$

PDF

$$f_k(x_1, \dots, x_k) = \int \dots \int_{\mathbb{R}^{m-k}} f_m(x_1, \dots, x_m) d\mu(x_{k+1}) \dots d\mu(x_m)$$

independence

X_1, \dots, X_m are independent iff $\exists G_1, \dots, G_m$ s.t.

$$\forall (x_1, \dots, x_m) \in \mathbb{R}^m, \quad F_m(x_1, \dots, x_m) = G_1(x_1) \dots G_m(x_m)$$

A similar factorization holds for the pdf

random vectors: An n -dim. random vector X is

just a sequence of n random variables $\vec{X} = (X_1, \dots, X_n)$

ex. for marginals

$$f(x, y) = \begin{cases} cx^2y & x^2 \leq y \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

what are the marginals? what is c ?

Moments

if it exists, The 1st moment or expectation of any r.v. X is given by

$$E(X) = \int_{\mathbb{R}} x dF(x)$$

More generally, if g is an integrable fn of X , then

$$E[g(X)] = \int_{\mathbb{R}} g(x) dF(x) \quad \text{ex. } X \sim U(-1, 1) \\ E(X^2) = ?$$

Ⓢ

$E[X^r]$ is the r^{th} moment of X , if it exists.
 $E[(X - E(X))^r]$ is the r^{th} central moment

$$\text{Variance of } X = \text{Var}(X) = E[(X - E(X))^2] \\ = E(X^2) - [E(X)]^2$$

For any 2 r.v.'s X and Y :

$$\text{Covariance}(X, Y) = \text{Cov}(X, Y) = E[(X - E(X))(Y - E(Y))] \\ = EXY - EXEY$$

For random vectors,

$$E(\underline{X}) = [E(X_1), \dots, E(X_n)]'$$

$$\text{Cov}(\underline{X}) = E[(\underline{X} - E(\underline{X}))(\underline{X} - E(\underline{X}))'] = \begin{bmatrix} \text{Var}(X_1) & \text{Cov}(X_1, X_2) & \dots & \text{Cov}(X_1, X_n) \\ & \dots & \dots & \dots \\ & & \dots & \dots \\ & & & \text{Var}(X_n) \end{bmatrix}$$

Def: $\underline{Y} = \underline{A}\underline{X} + \underline{b}$ $E(\underline{X}) = \underline{\mu}$
 $\begin{matrix} m \times n & n \times 1 & n \times 1 \\ & & n \times 1 \end{matrix}$ $\begin{matrix} n \times 1 \\ & & n \times 1 \end{matrix}$

Then $E(\underline{Y}) = \underline{A}\underline{\mu} + \underline{b}$ $\text{Cov}(\underline{Y}) = \underline{A}\underline{\Sigma}\underline{A}'$

Characteristic Functions / Moment Generating Functions

The characteristic fn of a r.v. X is a fn. $\phi(t) = E(e^{itX})$
 $= E(\cos tX) + iE(\sin tX)$

Properties:

The char fn. always exists, is defined $\forall t \in \mathbb{R}$
 one-to-one correspondence btw. CDFs and char fns.

X_1, \dots, X_k indep. w/ char fns. ϕ_1, \dots, ϕ_k , then
 $Y = X_1 + \dots + X_k$ has char fn. $\phi_Y(t) = \prod_{j=1}^k \phi_j(t)$

Main useful property

if $E(X^r)$ exists, then $E(X^r) = i^{-r} \left. \frac{d^r \phi_X(t)}{dt^r} \right|_{t=0}$

we'll return to this when we talk about the normal dist'n

Char fns easily extend to m -variate random vectors \underline{X} :

$$\phi(\underline{t}) = E(e^{i \underline{t}' \underline{X}}) \quad (\underline{X}_1, \dots, \underline{X}_m)$$

this can be used to find moments and cross-moments:

$$E\left(\prod_{j=1}^n X_j^{r_j}\right) = \frac{1}{i^{r_1 + \dots + r_n}} \left[\frac{\partial^{r_1 + \dots + r_n} \phi(\underline{t})}{\partial t_1^{r_1} \dots \partial t_n^{r_n}} \right]_{\underline{t}=\underline{0}}$$

Moment generating fns. are very similar. For a r.v. X , MGF

$$\psi(t) = E(e^{tX})$$

Unlike the char fn, the MGF may not exist, but if it does, we can use it to recover moments:

$$\psi'(0) = E(X) \quad \psi''(0) = E(X^2) \quad \psi'''(0) = E(X^3) \quad \dots$$

Other props:

① Sums of indep. r.v.'s ~~are~~ ^{has MGF that is the} product of MGF's

② $Y = aX + b$. $\forall t$ s.t. $\psi_X(at)$ exists, $\psi_Y(t) = e^{bt} \psi_X(at)$

PF.

$$\psi_Y(t) = E(e^{tY}) = E(e^{t(aX+b)}) = e^{bt} E(e^{atX}) = e^{bt} \psi_X(at)$$

Ex. Bernoulli ~~vars~~ distn

$$X = \begin{cases} 1 & \text{w/prob } p \\ 0 & \text{w/prob } q = 1-p \end{cases}$$

$$\begin{aligned} \text{MGF } \psi_X(t) &= E(e^{tX}) = pe^t + (1-p) \cdot 1 \\ &= pe^t + q \end{aligned}$$

with 1st 2 moments

$$E(X) = \psi'_X(0) = p$$

$$E(X^2) = \psi''_X(0) = p \Rightarrow \text{Var}(X) = p - p^2 = p(1-p) = pq$$

just as easy to do ~~with~~ these moments directly

Now suppose $Y = X_1 + \dots + X_n$, $X_i \stackrel{iid}{\sim} \text{Bernoulli}(p)$

Then by property ① above

$$\psi_Y(t) = (pe^t + q)^n$$

and

$$E(Y) = np \quad \text{var}(Y) = np(1-p)$$

~~The~~ Y has a binomial distn, with

$$f(x) = \begin{cases} \binom{n}{x} p^x q^{n-x} & \text{for } x = 0, 1, \dots, n \\ 0 & \text{otherwise} \end{cases}$$

Transformations of r.v.'s

Let f be the joint pdf of abs cts r.v.'s X_1, \dots, X_n

Suppose we want the joint pdf of r.v.'s Y_1, \dots, Y_n , where

$$Y_1 = g_1(\underline{X}), \dots, Y_n = g_n(\underline{X})$$

Let the xformation be one-to-one for some $R^0 \subset \mathbb{R}^n$ s.t. $\Pr(\underline{X} \in R^0) = 1$
(this assumption can be weakened considerably, cf. DeGroot (1970))

Then we can write the inverse

$$x_1 = h_1(y_1, \dots, y_n) \quad \dots \quad x_n = h_n(y_1, \dots, y_n)$$

Let

Assume partial derivatives of all h exist and are cts.

Define the Jacobian $J(y_1, \dots, y_n)$ as the determinant

$$\begin{vmatrix} \frac{\partial h_1}{\partial y_1} & \dots & \frac{\partial h_1}{\partial y_n} \\ \vdots & & \vdots \\ \frac{\partial h_n}{\partial y_1} & \dots & \frac{\partial h_n}{\partial y_n} \end{vmatrix}$$

If the Jacobian does not vanish at any (y_1, \dots, y_n)

then the pdf of Y is given by

$$f(y) = f[h_1(y), \dots, h_n(y)] |J(y)|$$

ex. $f(x_1, x_2) = \begin{cases} 4x_1x_2 & x_1, x_2 \in [0, 1] \\ 0 & \text{o.w.} \end{cases}$

$$Y_1 = \frac{X_1}{X_2} \quad Y_2 = X_1 X_2$$

Solve for the inverse: $X_1 = (Y_1 Y_2)^{1/2} \quad X_2 = \left(\frac{Y_2}{Y_1}\right)^{1/2}$

Jacobian

$$\begin{vmatrix} \frac{1}{2} \left(\frac{y_2}{y_1} \right)^{1/2} & \frac{1}{2} \left(\frac{y_1}{y_2} \right)^{1/2} \\ -\frac{1}{2} \left(\frac{y_2}{y_1} \right)^{1/2} & \frac{1}{2} \left(\frac{1}{y_1 y_2} \right)^{1/2} \end{vmatrix} = \frac{1}{2y_1}$$

Note the support for Y_1 and Y_2

$$Y_1 > 0, Y_2 > 0, Y_1 Y_2 < 1, \frac{Y_2}{Y_1} < 1$$

so $\left| \frac{1}{2y_1} \right| = \frac{1}{2y_1}$

and $f(y_1, y_2) = \begin{cases} 2 \left(\frac{y_2}{y_1} \right) & \text{(in the support)} \\ 0 & \text{otherwise} \end{cases}$

Conditional distributions

Let $X = (X_1, \dots, X_m)'$ and $Y = (Y_1, \dots, Y_n)'$ be 2 random vectors with joint pdf $f(\underline{x}, \underline{y})$ and marginal $g(\underline{y})$ for Y .

Then $\forall \underline{y}$ s.t. $g(\underline{y}) > 0$, the conditional dist'n $X | Y = \underline{y}$ has pdf

$$h(\underline{x} | \underline{y}) = \frac{f(\underline{x}, \underline{y})}{g(\underline{y})} \quad \text{or equivalently } f(\underline{x}, \underline{y}) = h(\underline{x} | \underline{y}) g(\underline{y})$$

Note that this event could have $\Pr = 0$, so this extends the earlier result on conditioning. Same extension for

Bayes Theorem

As above, but define $h_1(x|y)$, $h_2(y|x)$ as conditional pdf's and $g_1(x)$ and $g_2(y)$ as marginals. $\forall \underline{x}$ s.t. $g_1(\underline{x}) > 0$

$$h_2(y|x) = \frac{h_1(x|y) g_2(y)}{\int h_1(x|t) g_2(t) d\mu(t)}$$

Conditional Expectations

Again define X and Y as above; let $\phi(X, Y)$ be an integrable fn of X and Y .

Then the cond'l expectation of $\phi(X, Y)$ given Y is a fn. of Y .

ⓐ
$$E[\phi(X, Y) | Y] = \int_{\mathbb{R}^m} \phi(x, Y) h_1(x | Y) d\mu(x)$$

Law of iterated expectations:

$$E[E(\phi(X, Y) | Y)] = E[\phi(X, Y)]$$

Finally, if X and Y are scalars w/ $Var(X) < \infty$, then

$$Var(X) = E[Var(X | Y)] + Var[E(X | Y)]$$

Pf. Exercise

Ex. $X \sim U[0, 1]$. Then cond'l on X , $Y \sim U[\cancel{0, 1}] U[X, 1]$
what's the marginal dist'n of Y ?

Marginal^{pdf} of X is $g_1(x) = \begin{cases} 1 & x \in [0, 1] \\ 0 & \text{otherwise} \end{cases}$

Cond'l of Y is $h_2(y | x) = \begin{cases} \frac{1}{1-x} & x < y < 1 \\ 0 & \text{otherwise} \end{cases}$

Joint pdf is $f(x, y) = \begin{cases} \frac{1}{1-x} & 0 < x < y < 1 \\ 0 & \text{otherwise} \end{cases}$

Marginal of Y is $g_2(y) = \int f(x, y) dx = \int_0^y \frac{1}{1-x} dx = \begin{cases} -\ln(1-y) & y \in [0, 1] \\ 0 & \text{otherwise} \end{cases}$